## **SKYPER PRIME 1400A / 1700V ST10**



## IGBT Driver for SEMITRANS 10

Order Nr. L5066802

# **SKYPER PRIME 1400A / 1700V ST10**

#### **Features**

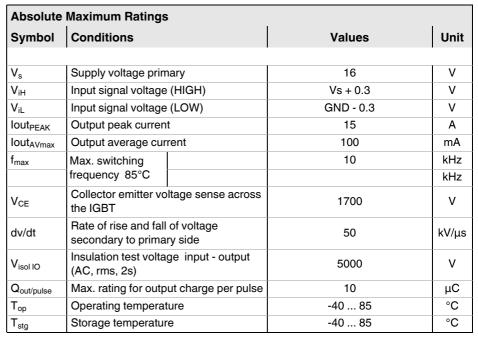
- Dynamic short circuit detection with SoftOff
- Galvanic isolated DC link measurement
- · Galvanic isolated temp measurement
- PWM output for sensor signals
- · Over voltage trip
- · ROHS, UL recognized
- DC Bus up to 1200V

#### Typical Applications\*

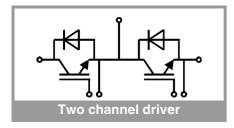
- · Regenerative inverters
- Traction
- Large drives

#### Remarks

- For environmental conditions please check technical explanation
- The driver has to be 100% tested for high voltage before use



| Characte                | Characteristics                                   |        |      |                   |      |  |  |  |
|-------------------------|---|--------|------|-------------------|------|--|--|--|
| Symbol                  | Conditions  | min.   | typ. | max.              | Unit |  |  |  |
|                         |   |        |      |                   | 1    |  |  |  |
| Vs                      | Supply voltage primary side                       | 14.4   | 15   | 15.6              | V    |  |  |  |
| I <sub>S0</sub>         | Supply current primary (no load)                  |        | 85   |                   | mA   |  |  |  |
|                         | Supply current primary side (max.)                |        |      | 1000              | mA   |  |  |  |
| $V_{i}$                 | Input signal voltage on / off                     | Vs/0   |      | V                 |      |  |  |  |
| $V_{\text{IT+}}$        | Input treshold voltage (HIGH)                     | 8.6 10 |      | V                 |      |  |  |  |
| $V_{\text{IT-}}$        | Input threshold voltage (LOW)                     | 5      |      | 6.7               | V    |  |  |  |
| R <sub>IN</sub>         | Input resistance (switching signal)               |        | 30   |                   | kΩ   |  |  |  |
| C <sub>IN</sub>         | Input capacitance (switching signals)             |        | 1    |                   | nF   |  |  |  |
| V <sub>G(on)</sub>      | Turn on output voltage                            |        | 15   |                   | V    |  |  |  |
| $V_{G(off)}$            | Turn off output voltage                           | -8     |      | V                 |      |  |  |  |
| t <sub>d(on)IO</sub>    | Input-output turn-on propagation time             | 1      |      | μs                |      |  |  |  |
| t <sub>d(off)IO</sub>   | Input-output turn-off propagation time            | 1      |      | μs                |      |  |  |  |
| t <sub>d(err)SCP</sub>  | Error sec - prim propagation time                 | 0.6    |      | μs                |      |  |  |  |
| t <sub>d(err)HALT</sub> | Error primary - secondary side propagation time   | 0.6    |      | μs                |      |  |  |  |
| t <sub>TD</sub>         | Top-Bot interlock dead time                       | 4      |      | μs                |      |  |  |  |
| t <sub>jitter</sub>     | Signal transfer prim - sec (total jitter)         | 25     |      | ns                |      |  |  |  |
| t <sub>SIS</sub>        | Short pulse suppression                           | 0.4    |      | μs                |      |  |  |  |
| t <sub>POR</sub>        | Power-On-Reset completed                          | 0.1    |      | S                 |      |  |  |  |
| t <sub>pRESET</sub>     | Error reset time                                  | 0.03   |      |                   | ms   |  |  |  |
| V <sub>CEstat</sub>     | Reference voltage for V <sub>CE</sub> -monitoring |        | 8.5  |                   | V    |  |  |  |
| t <sub>bl</sub>         | VCE monitoring blanking time (dynamic)            | 4      |      | μs                |      |  |  |  |
| $V_{DCtrip}$            | Over voltage trip level                           | 1250   |      | V                 |      |  |  |  |
| R <sub>Gon</sub>        | Driver gate resistor at switch-on                 | 3      |      | Ω                 |      |  |  |  |
| R <sub>Goff</sub>       | Driver gate resistor at switch-off                | 0      |      | Ω                 |      |  |  |  |
| MTBF                    | Mean Time Between Failure Ta = 40°C               | 3      |      | 10 <sup>6</sup> h |      |  |  |  |



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#### **Signal Connector**

| PIN   | Signal        | Function                                 | Specifications                                   |  |
|-------|---------------|--|--|--|
| X1:01 | IF_PWR_15P    | Drive power supply                       | Stabilised +15V ±4%                              |  |
| X1:02 | IF_DC_LINK    | Digitised DC Link signal                 | PWM output, 15V                                  |  |
| X1:03 | IF_PWR_15P    | Drive power supply                       | Stabilised +15V ±4%                              |  |
| X1:04 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:05 | IF_PWR_15P    | Drive power supply                       | Stabilised +15V ±4%                              |  |
| X1:06 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:07 | IF_nERROR_IN  | ERROR input                              | LOW ( GND, U <sub>TH</sub> 1V ) = External error |  |
|       |               |  | HIGH (VP, U <sub>TH</sub> 14V) = No error        |  |
|       |               |  | Max input current 1,8mA, can be                  |  |
|       |               |  | connected with IF_nERROR_OUT                     |  |
| X1:08 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:09 | IF_nERROR_OUT | ERROR output                             | HIGH = NO ERROR ;open collector output           |  |
|       |               |  | 15V / 10mA (external pull up                     |  |
|       |               |  | Resistor necessary )                             |  |
| X1:10 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:11 | IF_HB_TOP     | Switching signal input ( TOP switch )    | Positive 15V CMOS logic,                         |  |
|       |               |  | LOW = TOP switch off;                            |  |
|       |               |  | HIGH = TOP switch on                             |  |
| X1:12 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:13 | IF_nERROR_OUT | ERROR output                             | HIGH = NO ERROR; open collector                  |  |
|       |               |  | output; max. 15V / 10 mA (external               |  |
|       |               |  | pull up resistor necessary)                      |  |
| X1:14 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:15 | IF_HB_BOT     | Switching signal input ( BOTTOM switch ) | Positive 15V CMOS logic,                         |  |
|       |               |  | LOW = BOT switch off;                            |  |
|       |               |  | HIGH = BOT switch on                             |  |
| X1:16 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:17 | IF_CFG_SELECT | Interlock set up                         | HIGH (VP) = No interlock                         |  |
|       |               |  | LOW (GND) = Interlock 4µs                        |  |
| X1:18 | IF_GND        | GND                                      | To be connected to ground                        |  |
| X1:19 | IF_TEMP       | Digitised NTC signal                     | PWM output, 15V                                  |  |
| X1:20 | IF_GND        | GND                                      | To be connected to ground                        |  |
|       |               |  |  |  |

This is an electrostatic discharge sensitive device (ESDS), international standard IEC 60747-1, chapter IX.

#### \*IMPORTANT INFORMATION AND WARNINGS

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